

Heterogeneity-Guided Tensor Decomposition for Traffic Flow Imputation

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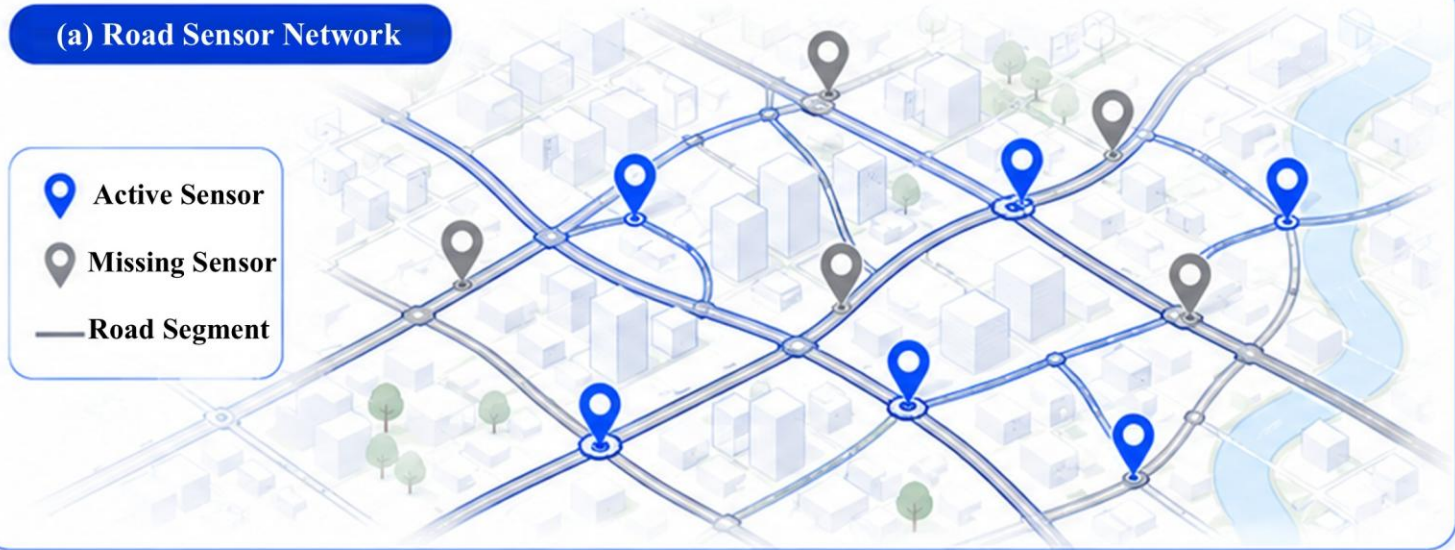
GeoAI 2026



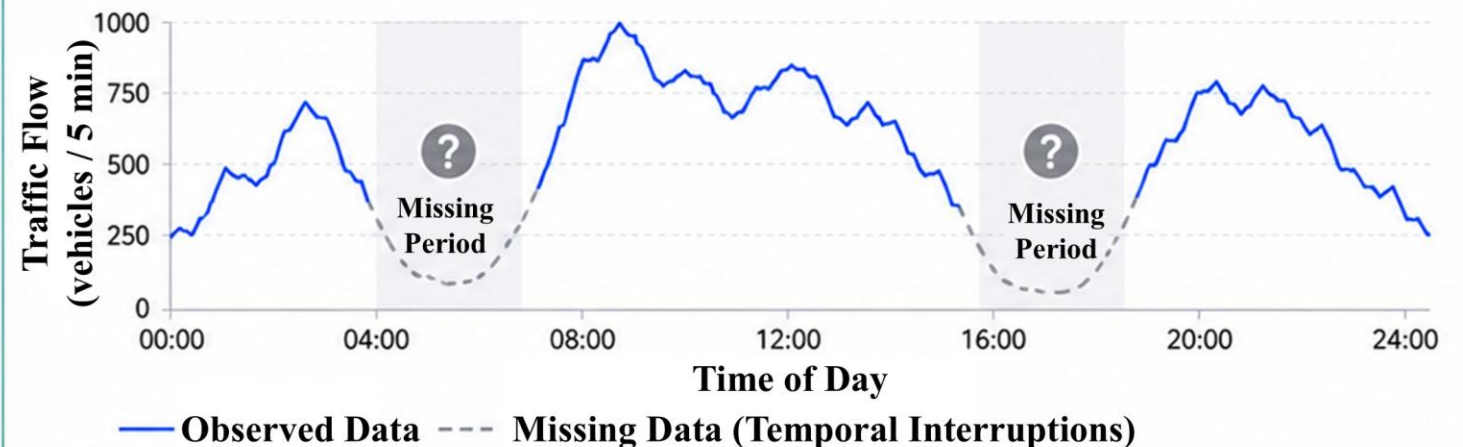
Background

- Traffic flow data support **urban mobility analysis** and **intelligent transportation systems**.
- However, fixed sensors often suffer from **uneven spatial coverage** and **temporal interruptions**.
- Traffic flow imputation is an important task for **GeoAI** and **intelligent transportation systems**.

(a) Road Sensor Network



(b) Traffic Flow Data(Example Sensor)



Core Challenge



Traffic flow patterns vary across **different locations and time periods**.



Even geographically similar regions can exhibit **different traffic patterns**.



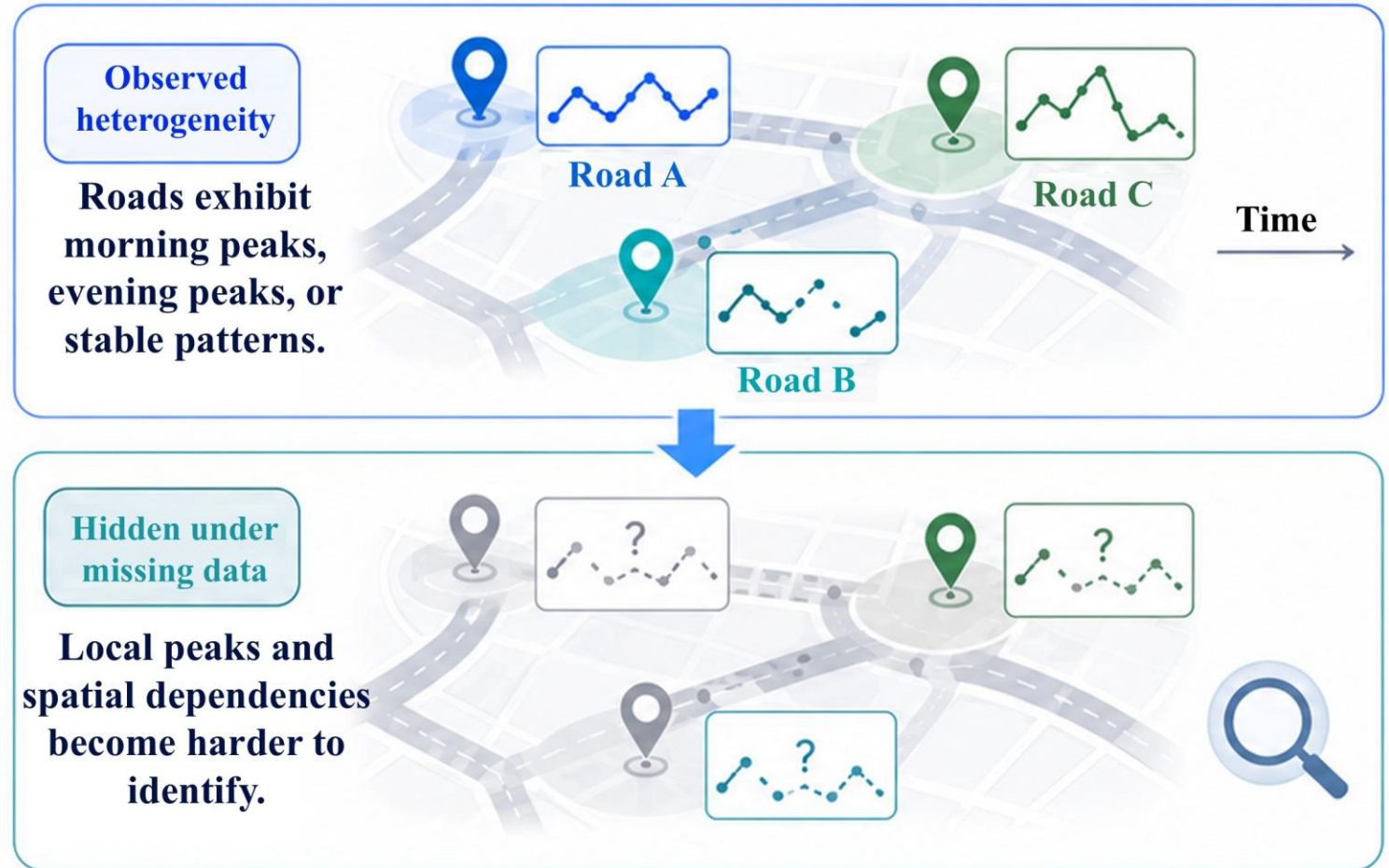
Missing data **obscure local temporal peaks and spatial dependencies**.



Therefore, **imputation** is not only a **reconstruction** problem, but also a **heterogeneity representation** problem.



Missing values make heterogeneity harder to identify, while poor heterogeneity modeling further weakens imputation

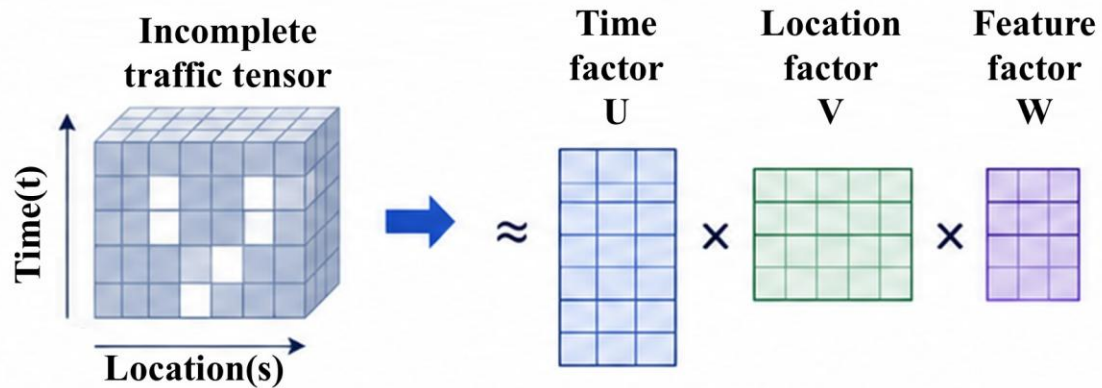


Limitation of Existing Methods



Existing tensor decomposition

- 1 Captures low-rank spatiotemporal structures
- 2 Efficient and interpretable
- 3 Often uses spatial similarity constraints



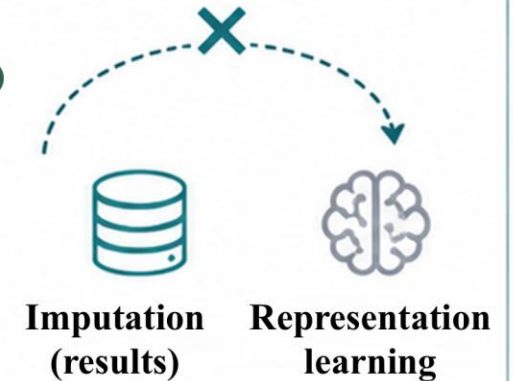
Limitations

- 1 Static similarity assumptions
- 2 Limited ability to represent missing-location heterogeneity
- 3 Lack of feedback from imputation results to representation learning

Observed similarity
(static assumption)



Missing locations
(high uncertainty)



This creates a gap between heterogeneity representation and missing data imputation

Research Question



This study asks a central research question:



How can we **learn spatiotemporal heterogeneity** from incomplete traffic data and use it to **guide tensor decomposition**?



To answer this question, we need three abilities:

1



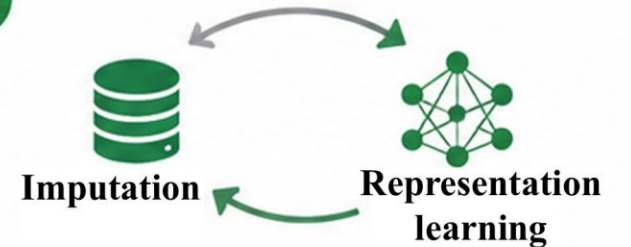
First, the model should **capture traffic patterns** under missing data.

2



Second, it should **represent spatial and temporal heterogeneity** explicitly.

3

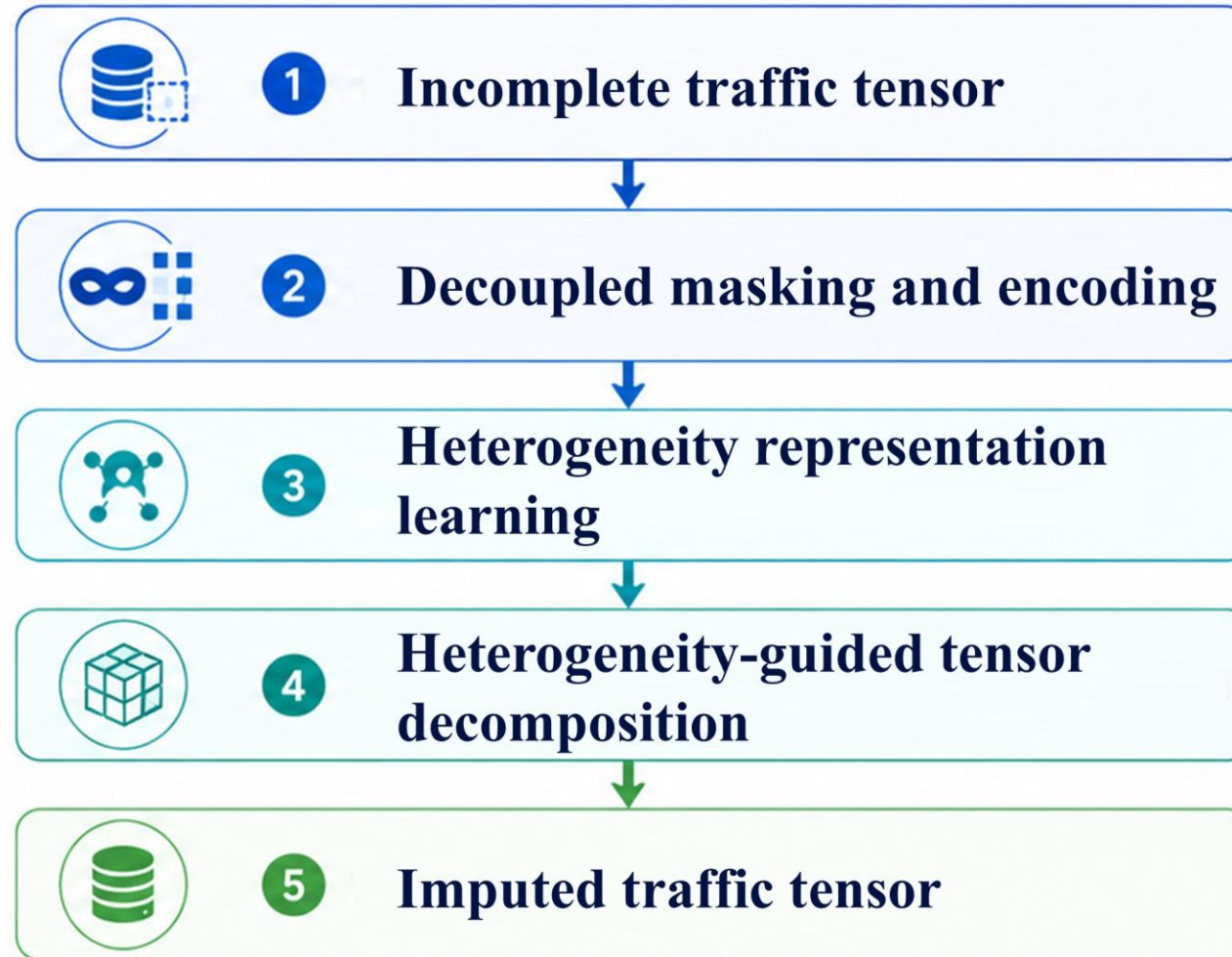


Third, it should allow **imputation and representation learning** to improve each other.



Our answer is a **heterogeneity-guided tensor decomposition** framework, named **Hg-TD**

Overview of Hg-TD



The key idea is to make heterogeneity representation and imputation mutually reinforced

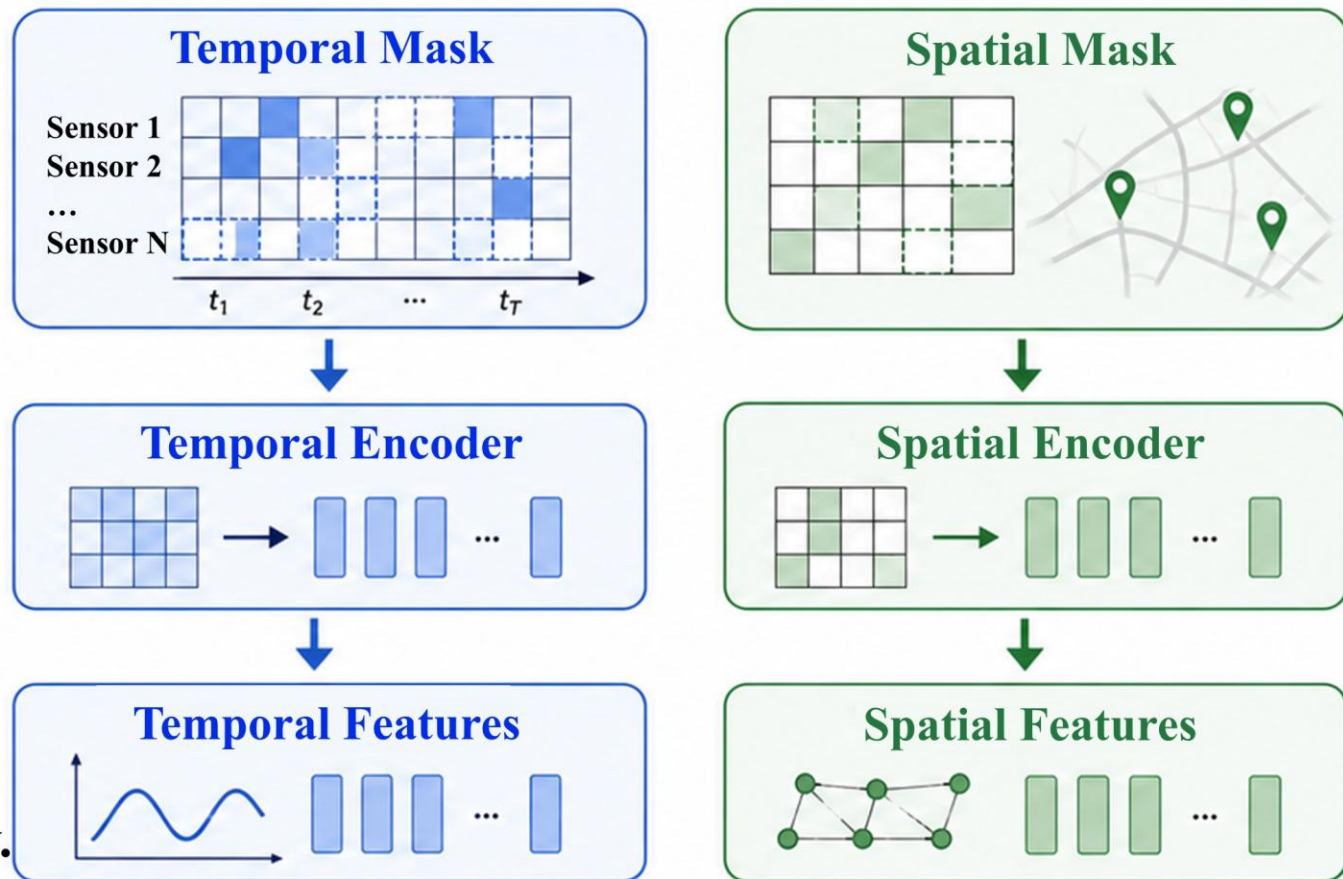
Component 1: Decoupled Masking and Encoding

Temporal and spatial missingness influence traffic patterns in different ways.

Therefore, Hg-TD does not use a **single unified** masking strategy.

Hg-TD **separately masks and encodes** the temporal and spatial dimensions.

This design helps the model learn **temporal periodicity and spatial locality** more clearly.



Decoupled masking provides a cleaner input for learning heterogeneous traffic patterns

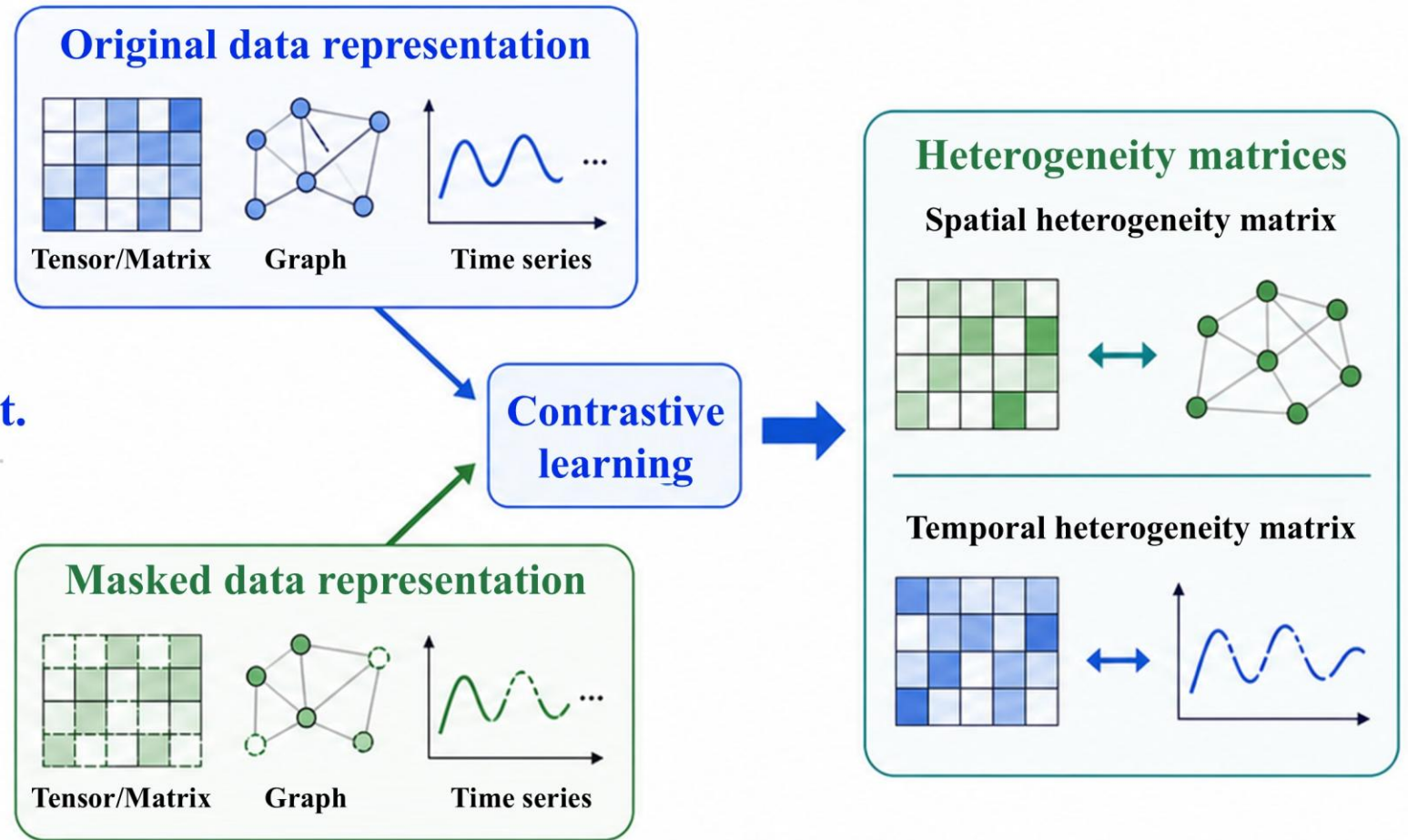
Component 2: Learning Heterogeneity Under Missing Data

Hg-TD **learns heterogeneity** by comparing representations from original data and masked data.

The model can recover similar heterogeneity structures from masked inputs, then **the learned representation becomes more robust**.

Masked contrastive learning provides a **self-supervised signal** for missing locations.

The output is a set of **spatial and temporal heterogeneity matrices**.



These matrices describe how traffic relationships vary across sensors and time periods

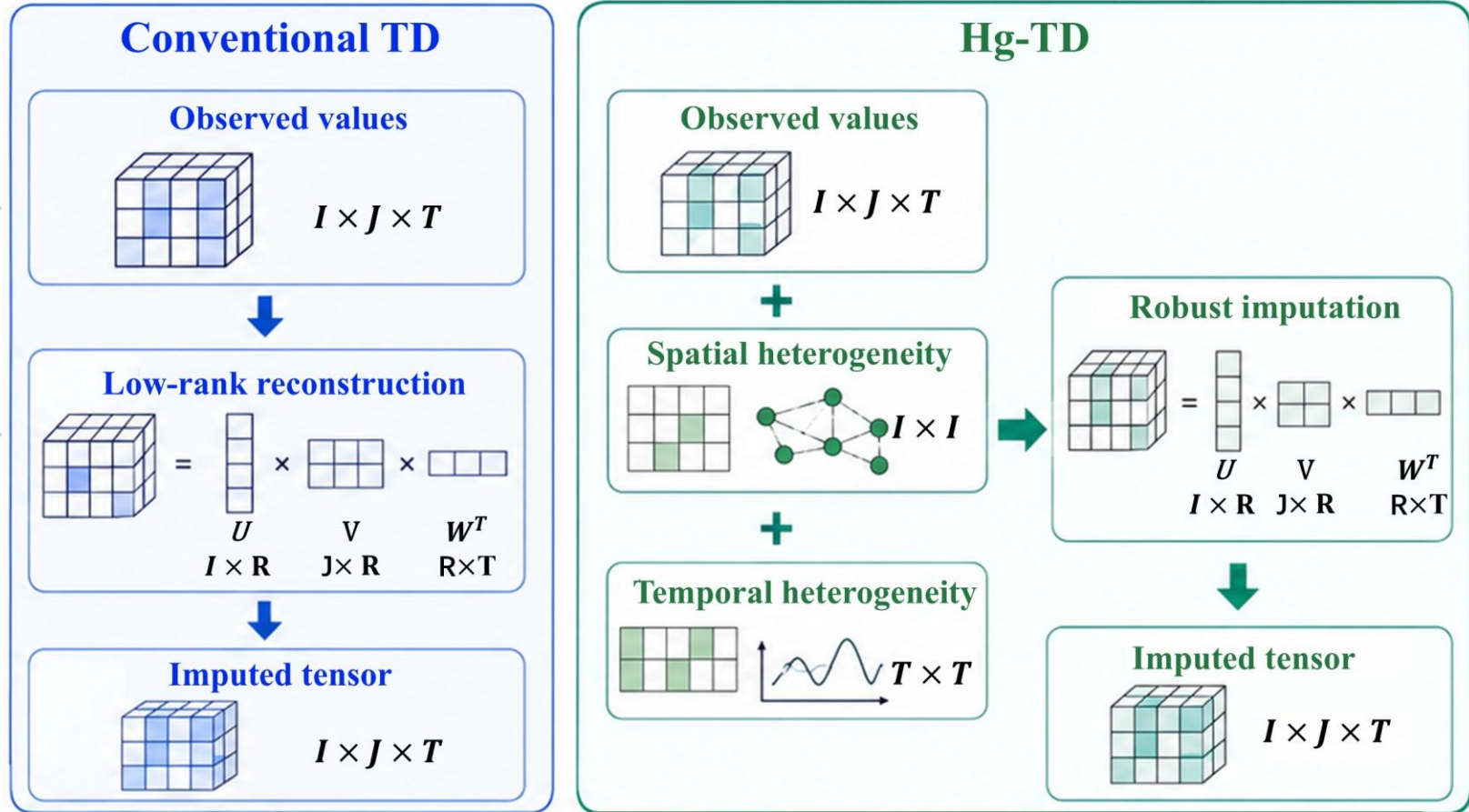
Component 3: Heterogeneity-Guided Tensor Decomposition

In conventional TD, factor matrices are **optimized to fit** the observed traffic values.

In Hg-TD, the factor matrices are **constrained by** the learned heterogeneity matrices.

The **spatial heterogeneity** matrix guides the model to capture **relationships** among road sensors.

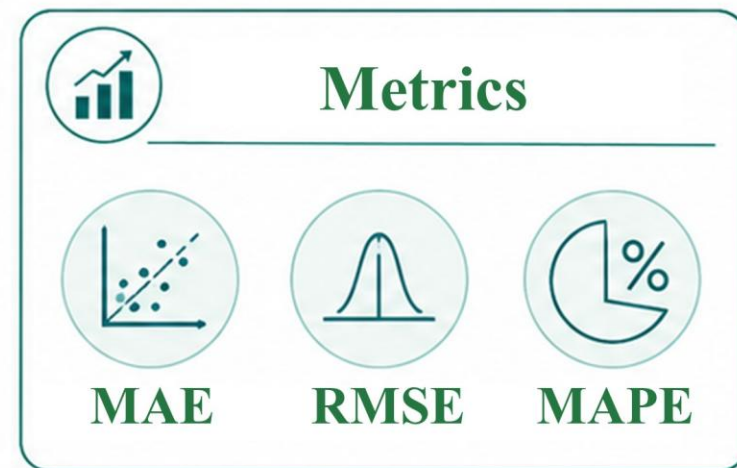
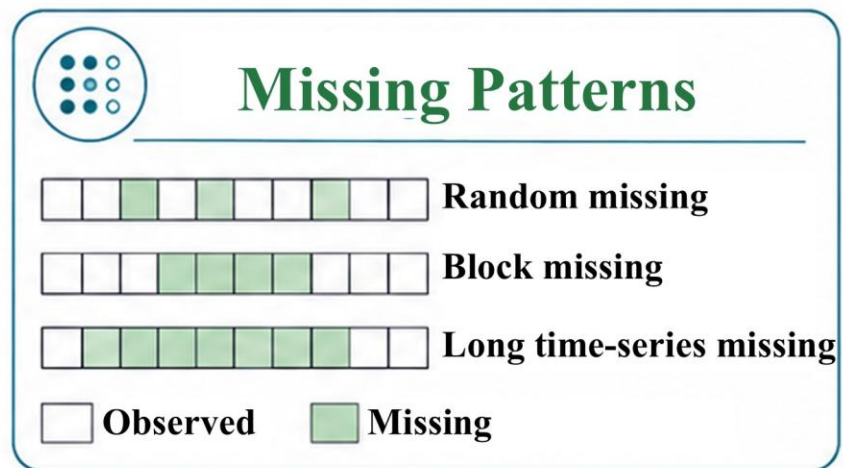
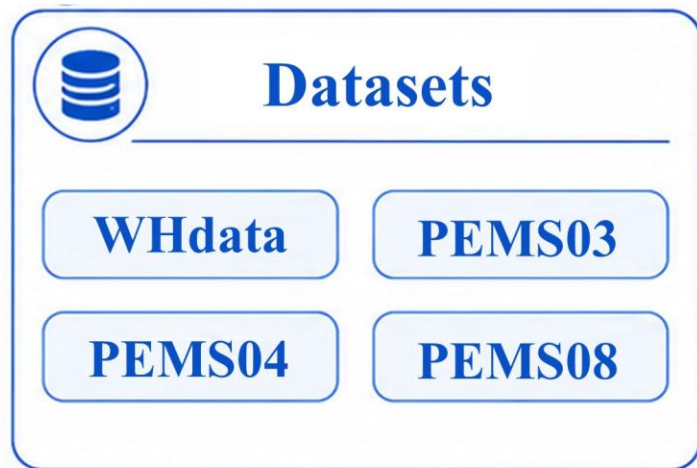
The **temporal heterogeneity** representation helps the model **adapt to** traffic changes over time.



Tensor decomposition becomes heterogeneity-aware rather than only correlation-based

Experimental Setup

- ❑ We evaluated Hg-TD on four real-world traffic flow datasets: **WHdata**, **PEMS03**, **PEMS04**, and **PEMS08**.
- ❑ Three missing patterns were considered: **random missing**, **block missing**, and **long time-series missing**.
- ❑ The model was compared with **statistical methods**, **deep learning models**, and **tensor decomposition baselines**.
- ❑ We used **MAE**, **RMSE**, and **MAPE** as evaluation metrics.



Baselines: statistical methods, deep learning models, and tensor decomposition methods.



This setup tests both accuracy and robustness under diverse missing scenarios

Baseline Model Comparison

Method	RM	BM	TM
	Friedman's test		
	$\chi^2 = 62.5804$	$\chi^2 = 148.3649$	$\chi^2 = 152.6141$
	p (Cohen's d)		
HA	0.00019***(-2.363)	0.00019*** (-2.363)	0.00016***(-2.183)
SES	0.00033***(-2.320)	0.00033***(-2.320)	0.00026***(-2.196)
KNN	0.00039***(-1.033)	0.00039***(-1.033)	0.00002***(-0.642)
BRITS	0.03103*(-1.252)	0.03103*(-1.252)	0.02879*(-1.262)
USGAN	0.03103*(-1.240)	0.03103*(-1.240)	0.00864**(-1.587)
BGCP	0.01038*(-0.048)	0.01038*(-0.048)	0.00864**(-0.123)
BTTF	0.00203**(-0.156)	0.00203**(-0.156)	0.02879*(-0.206)
BATF	0.00638**(-0.056)	0.00638**(-0.056)	0.00864**(-0.131)
BTMF	0.00073***(-0.349)	0.00073***(-0.349)	0.00736**(-0.113)
LAMC-TNN	0.03103*(-0.605)	0.03103*(-0.605)	0.02879*(-0.381)
LRTC-TNN	0.00514**(-0.065)	0.00514**(-0.065)	0.02879*(-0.963)
Meta-TD	0.03103*(-0.034)	0.03103*(-0.034)	0.02879*(-0.060)



We compare **Hg-TD** with statistical, deep learning, and tensor decomposition baselines.



Hg-TD achieves the **best overall performance** across four real-world datasets.



The improvement becomes larger when the **missing rate increases**.



This shows the value of heterogeneity modeling **under severe missingness**.

Statistical Significance Test

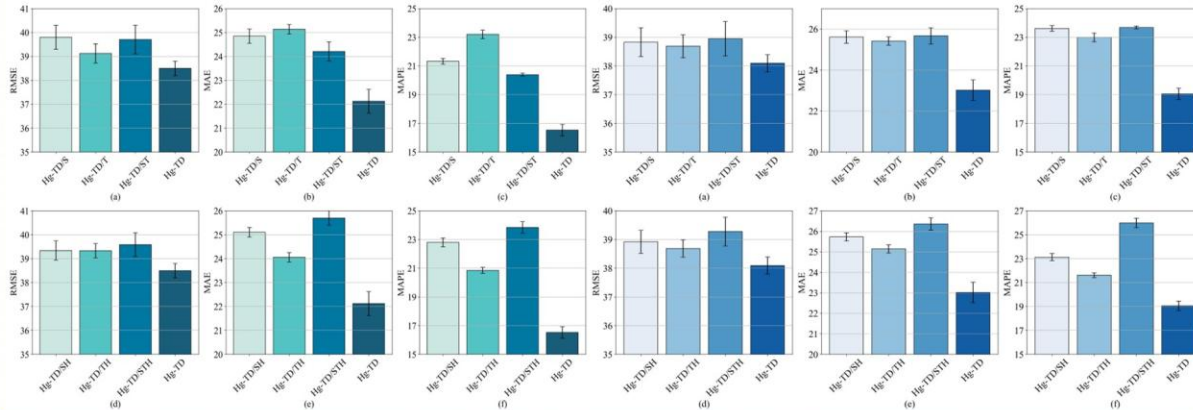


Hg-TD consistently improves imputation accuracy, especially under high missing rates

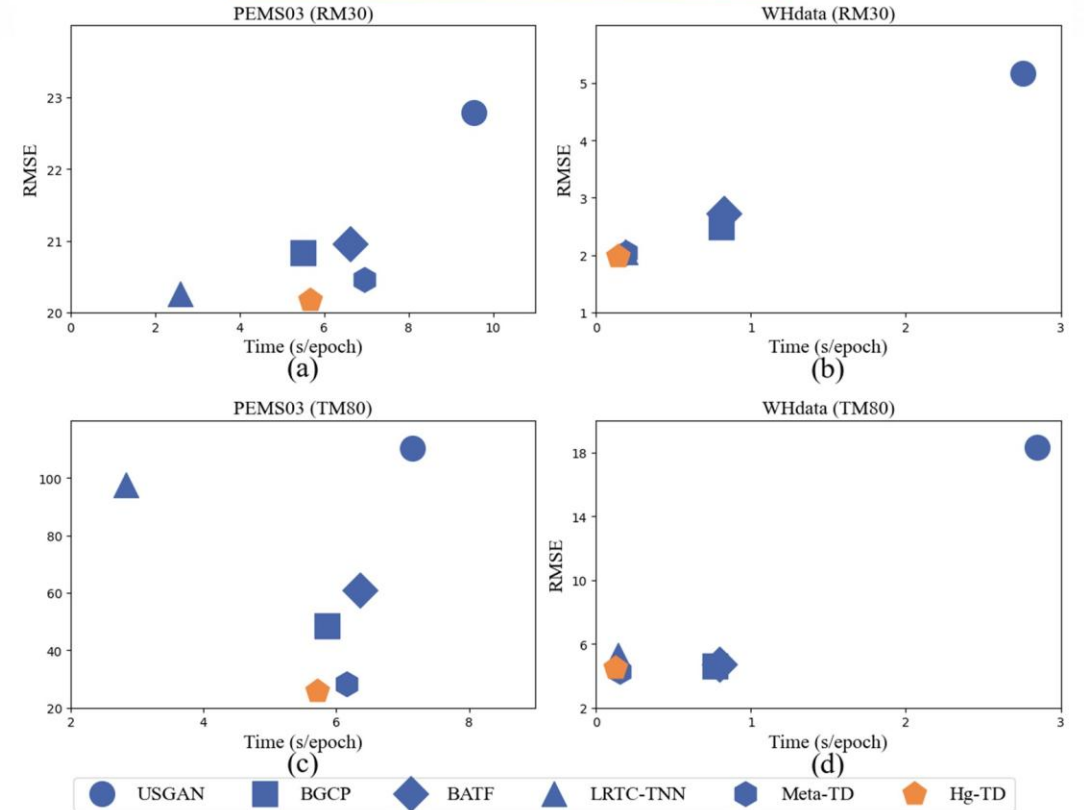
Ablation Study and Computational Complexity

Ablation Study

- Each component contributes to the final performance.
- **Without decoupled masking**, the model becomes less effective in separating temporal and spatial patterns.
- **Without contrastive learning**, the learned representation becomes less robust under missing data.
- **Without heterogeneity constraints**, tensor decomposition loses important guidance from traffic dynamics.



Complexity Analysis



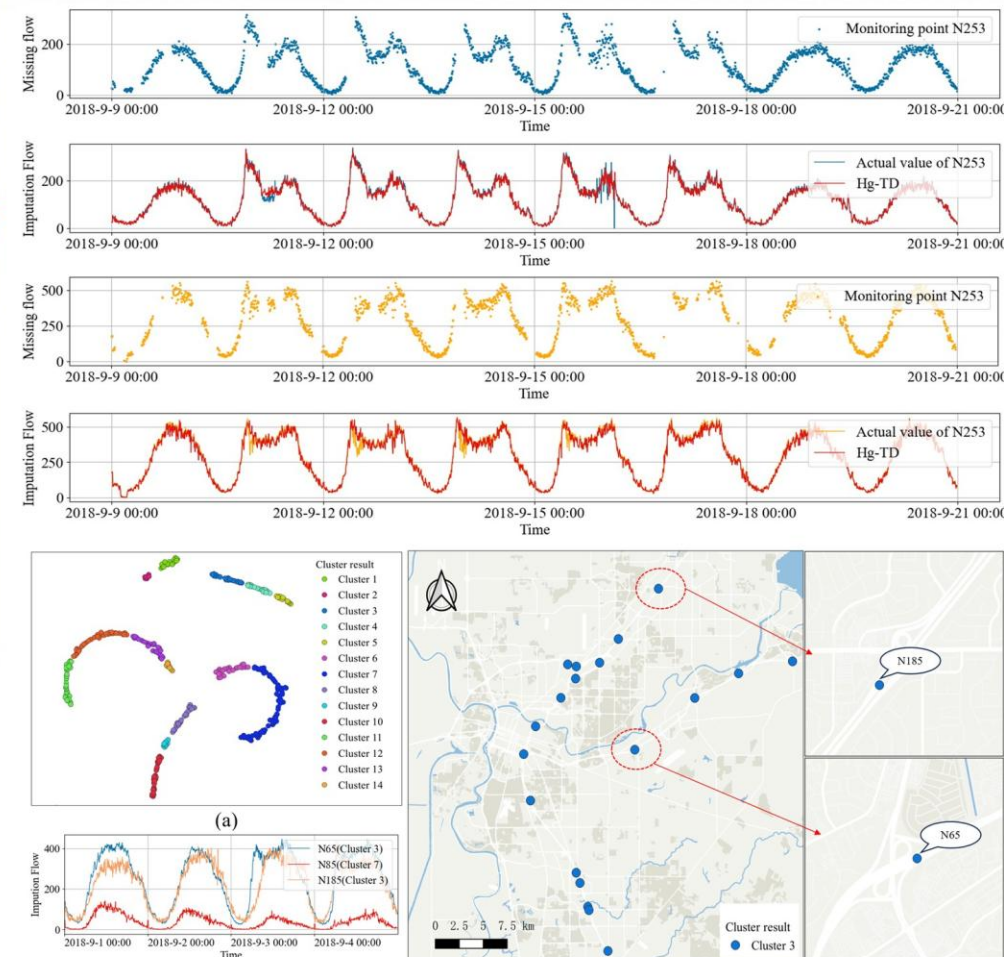
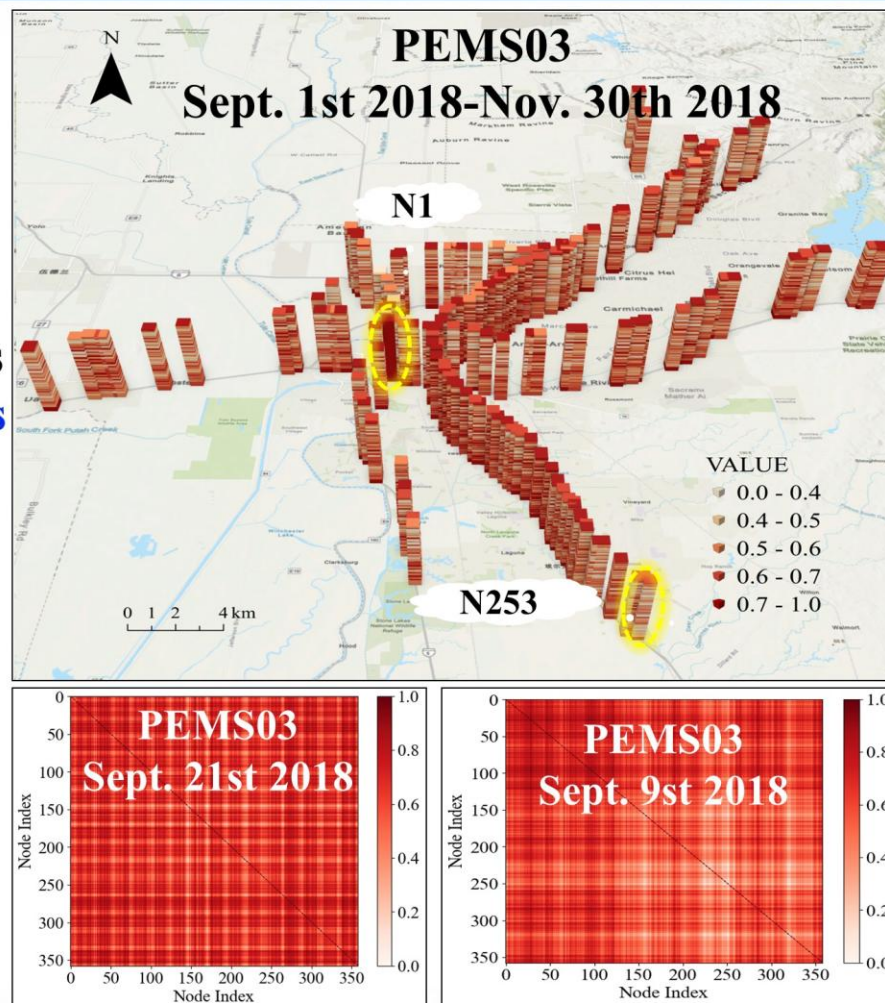
Hg-TD balances imputation accuracy and computational cost.



The full Hg-TD framework is both effective and computationally practical

Effectiveness of Representation Learning

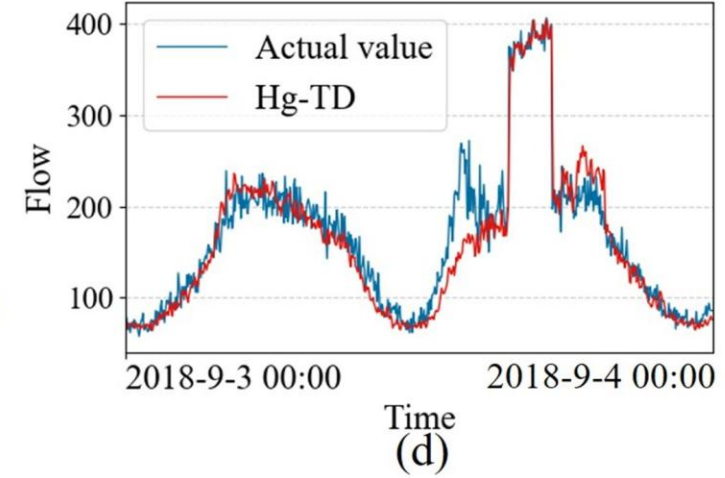
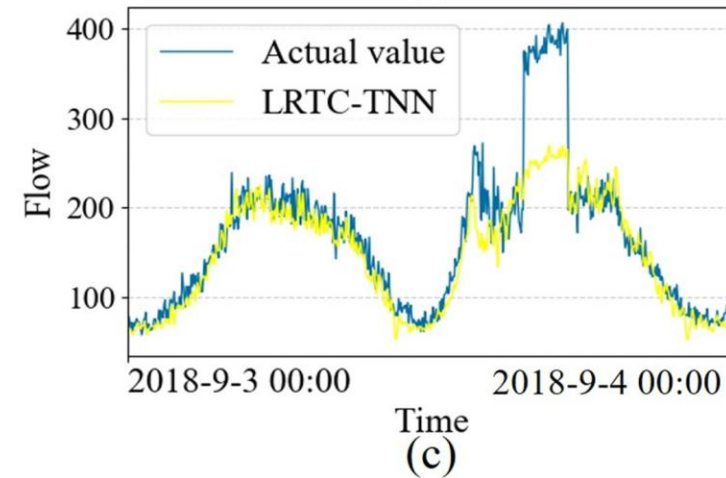
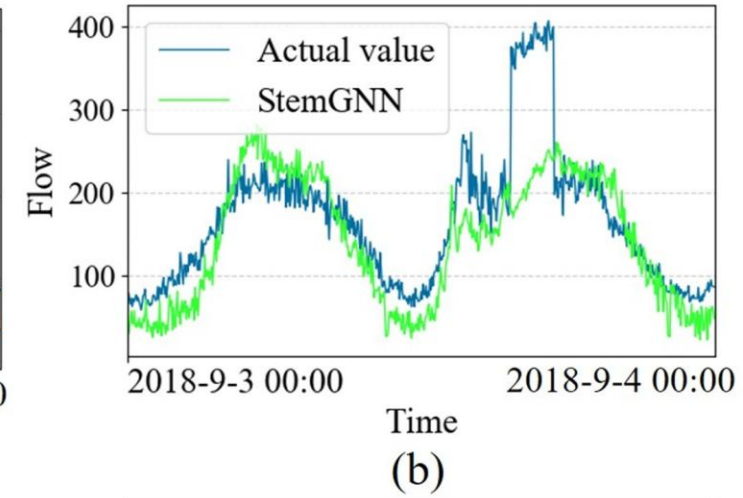
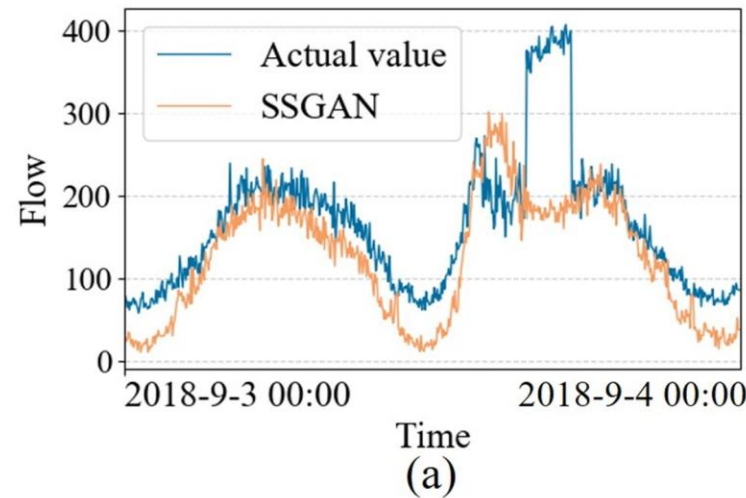
- We examine whether Hg-TD learns **meaningful heterogeneity representations**.
- The spatial matrix reveals **non-uniform relationships** among traffic sensors.
- The temporal representation captures changes between **peak and off-peak** periods.
- These representations provide **useful guidance** for tensor decomposition.



Hg-TD learns interpretable spatiotemporal heterogeneity for traffic imputation

Case Study

- We use a representative case to visualize the imputation results.
- Baseline methods tend to smooth local traffic variations.
- Hg-TD better reconstructs **peak-hour changes and local fluctuations**.
- This produces **more realistic traffic flow patterns**.



Hg-TD better preserves local traffic dynamics in heterogeneous missing-data scenarios

Conclusion



This study reformulates traffic flow imputation as a **heterogeneity-aware** spatiotemporal inference problem.



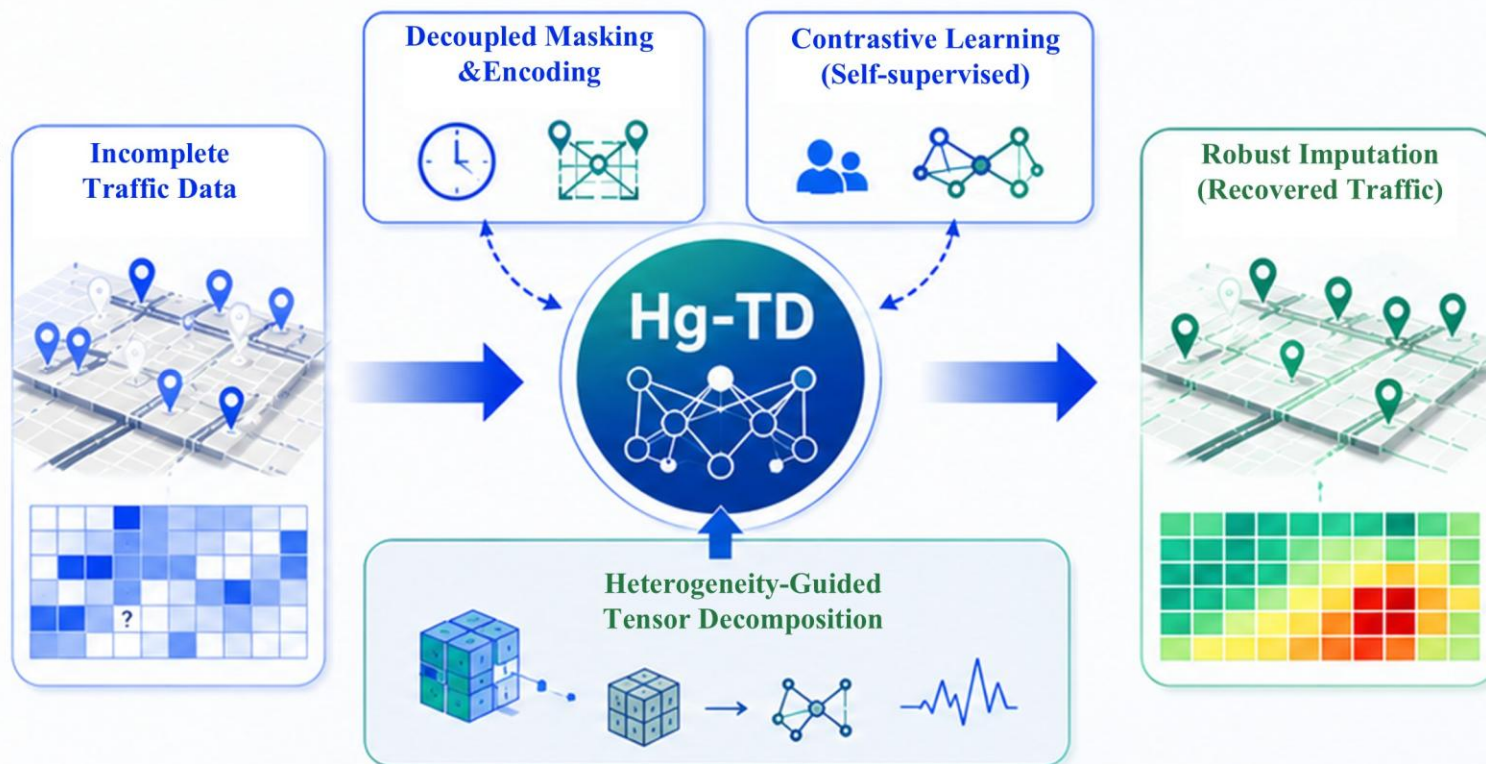
We propose **Hg-TD**, which learns **spatial and temporal heterogeneity** from incomplete traffic data.



The learned heterogeneity representations are embedded into tensor decomposition as **adaptive constraints**.



Experiments on four real-world datasets demonstrate improved **accuracy** and **robustness** under diverse missing patterns.



01 Problem

Missing data with heterogeneity



02 Method

Self-supervised heterogeneity-guided tensor decomposition



03 Result

Robust imputation under diverse missing patterns



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Thank you!

Q&A